# Asterx-m3 Pro+ Best-in-class dual-antenna multi-frequency GNSS receiver













AsteRx-m3 Pro+ is Septentrio's best-in-class versatile OEM board. It is a multi-frequency multi-constellation GNSS receiver featuring top positioning performance with flexibility to be used either as a base station or a rover receiver. In dual antenna mode it provides heading & pitch or heading & roll information on top of reliable and accurate positioning.

#### **KEY FEATURES**

- Flexibility of use and easy-to-integrate
- Best-in-class SWaP (Size, Weight and Power)
- AIM+ industry-leading anti-jamming, anti-spoofing technology
- OSNMA Support
- Full-constellation, multi-frequency satellite tracking
- Sub-degree GNSS heading & pitch or heading & roll
- High update rate with low latency

#### **Top performance in challenging environments**

The AsteRx-m3 Pro+ is designed to deliver reliable and robust positions even in challenging environments.

The GNSS+ toolset is the technology that allows AsteRx-m3 Pro+ to be reliable also in challenging environments where the GNSS signal is disturbed or the receiver is subject to shocks and vibrations:

- ▶ **LOCK+** for robust tracking during high vibrations and shocks
- ► APME+ to disentangle direct signal and those reflected from nearby structures
- ▶ IONO+ provides advanced protection against ionospheric disturbance
- ▶ **AIM+** most advanced anti-jamming, anti-spoofing on-board interference mitigation technology on the market (narrow and wide band, chirp jammers).

#### **BENEFITS**

### State of the art with flexibility of use

The AsteRx-m3 Pro+ is a state-of-the-art GNSS receiver using multi-constellation GNSS technology for maximal positioning availability and reliability in challenging conditions. It can be used as a base station or a rover receiver in single or dial antenna configuration. In dual antenna mode GNSS heading provides unmatched performance in both static and dynamic conditions removing the reliance on vehicle dynamics or magnetic sensors.

Such a versatile receiver allows integrators to keep a single item in stock which can be used in a multitude of applications. During the manufacturing process the needed features can be activated depending on the intended application.

#### **Ultra-low power design**

The AsteRx-m3 Pro+ provides RTK positioning at the lowest power consumption of any comparable device on the market. This means longer operation on a single battery charge, smaller batteries and greater usability.

## **Easy-to-integrate**

The AsteRx-m3 Pro+ comes with fully documented interfaces, commands and data messages. The included RxTools software allows receiver configuration and monitoring as well as data logging and analysis. An SDK is provided, which allows integrators to create professional custom post-processing applications. AsteRx-m3 Pro+ is compatible with its SDK library for PPK (Post-processed kinematic) offline processing.

# PHYSICAL AND ENVIRONMENTAL

47.5 x 70 x 9.32 mm

Power consumption

GPS L1/L2 750 mW
GPS/GLO L1/L2 800 mW
All signals, all GNSS 1000 mW
constellations

#### Antenna

Size

0.6 cm + 0.5 ppm

Heading

0.15°

0.03°

Horizontal

1.2 m

0.6 m

 $0.4 \, \text{m}$ 

1 cm + 1 ppm

Pitch/Roll

0.25°

0.05°

Vertical

1.9 m

0.8 m

 $0.7 \, \text{m}$ 

0.03m/s

100 Hz

100 Hz

<10 ms

5 ns

< 20 ns

< 45.5

< 20 s

avg. 1 s

20 dB-Hz

33 dB-Hz

7 s

Connectors<sup>8</sup> 2 x MMCX
Antenna supply voltage 3-5.5 VDC
Maximum antenna current 150 mA
Antenna gain range 15-45 dB

#### I/O connectors 9

30 Pins Hirose DF40 socket

60 Pins Hirose DF40 socket for expanded connectivity

#### **Environment**

Operating temperature  $-40^{\circ}$  C to  $+85^{\circ}$  C  $-40^{\circ}$  F to  $+185^{\circ}$  F

Storage temperature -55° C to +85° C

-67° F to +185° F

Humidity 5% to 95% (non-condensing)
Vibration MIL-STD-810G

#### Certification

RoHS, WEEE, CE, FCC, UKCA, ISO 9001-2015





#### Open sky conditions

- <sup>2</sup> RMS level
- <sup>3</sup> Baseline < 40 Km
- 4 99.9%
- $^{\rm 5}\,$  Including software compensation of sawtooth effect
- <sup>6</sup> No information available (no almanac, no approximate position)
- $^{\scriptscriptstyle 7}$  Ephemeris and approximate position known
- <sup>8</sup> Second connector for heading configuration
- Backwards compatible with AsteRx-m for easy replacement

#### **FEATURES**

#### **GNSS** signals

544 Hardware channels for simultaneous tracking of most visible signals:

- ► GPS: L1 C/A, L1C, L2C, L2 P(Y), L5
- ▶ GLONASS: L1 C/A, L2C/A, L3, L2P
- ▶ BeiDou: B1I, B1C, B2a, B2b, B2I, B3I
- ▶ Galileo: E1, E5a, E5b, E6
- QZSS: L1 C/A, L1 C/B, L2C, L5
- NavIC: L5
- ► SBAS: EGNOS, WAAS, GAGAN, MSAS, SDCM

#### Septentrio's patented GNSS+ technologies

- AIM+ industry leading anti-jamming, anti-spoofing interference monitoring & mitigation technology
- ▶ IONO+ advanced scintillation mitigation
- ► **APME+** a posteriori multipath estimator for code and phase multipath mitigation
- ► **LOCK+** superior tracking robustness under heavy mechanical shocks or vibrations
- ► **RAIM+** (Receiver Autonomous Integrity Monitoring)

OSNMA Support

#### **Formats**

Septentrio Binary Format (SBF), fully documented with sample parsing tools
NMEA 0183, v3.01, v4.0

DTCM v2 v v2 v (MCM m

RTCM v2.x, v3.x (MSM messages included) CMR v2.0 and CMR+ (CMR+ input only)

#### Connectivity

4 Hi-speed serial ports (LVTTL)

1 USB device port (TCP/IP communication and with 2 extra serial ports)

xPPS output (max 100Hz)

Ethernet port (TCP/IP, UDP, LAN 10/100 Mbps)

2 Event markers

Outputs to drive external LEDs

General purpose output

NTRIP (server, client, caster)

FTP server, FTP push, SFTP

#### SUPPORTING COMPONENTS

Web UI with full control and monitoring functionality.

RxTools, a complete and intuitive GUI tool set for receiver control, monitoring, data analysis and conversion.

GNSS receiver communication SDK. Available for both Windows and Linux

#### **OPTIONAL ACCESSORIES**

**PERFORMANCE** 

RTK performance 1,2,3

GNSS attitude accuracy 1,2

Horizontal accuracy

Antenna separation

Position accuracy 1,2

Velocity accuracy 1,2

Maximum update rate

Vertical accuracy

Initialisation

Standalone

**SBAS** 

**DGNSS** 

Position

Latency 4

xPPS out⁵

Cold start<sup>6</sup>

Warm start7

Tracking

Acquisition

Re-acquisition

Measurements

**Time precision** 

Event accuracy

Time to first fix

1 m

5 m

- Antennas
- SDK library for UAS applications

Tracking performance (C/N0 threshold)

Robotics interface board

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